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Materials and specifications are subject to change without manufacturer's obligation.



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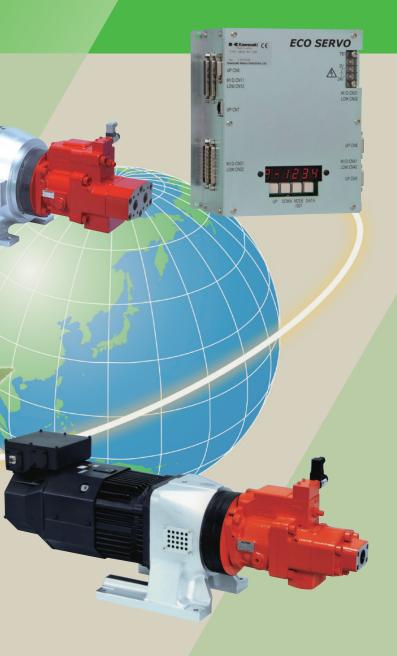
Unique Fluid Power Solution combines low energy consumption with high precision control!

Electro-Hydraulic hybrid system ECO SERVO

eco







When you are addressing engineering challenges such as:



<KAWASAKI's unique electro-hydraulic hybrid system defined>

- The electro-hydraulic hybrid system controls the speed of the electric motor directly coupled to the hydraulic pump in accordance with the power requirement in order to control the discharge from the hydraulic pump. We call this unique system "ECO SERVO".
- This system allows the users to build a hybrid system that features advantages of both hydraulic and electric control systems.
- With ECO SERVO, the user can control hydraulic equipment while fully making use of the advantages unique to hydraulic systems with ease as if the user is handling an electric drive system.

<Conventional system> Power loss on standby! 0 С



By controlling the speed of an electric motor, a hydraulic pump is run only when hydraulic power is necessary; as a result, the required power consumption is much reduced

<Benefits of ECO SERVO>

- ECO SERVO employs the KAWASAKI piston pump K3VR, K3VL, K7VG series product that boasts good reputation for their high pressure rating, high capacity and high efficiency. Peak pressure: 35 MPa, Max. discharge: 600 L/min (pump displacement: 500 cm³)
- Applicable to both open and closed circuits ECO SERVO series products include not only the standard pump intended for open circuits but also special pumps (with suction valve) intended for reversible high-pressure and closed circuits. ECO SERVO can be applied to a diversity of hydraulic circuits.
- Variable displacement pump is employed. Through use of a variable displacement pump that is capable of two displacement settings, the necessary drive torgue can be lower and the necessary motor capacity can be smaller.
- Applicable to both servo drive and inverter drive.

The initial cost is high.

The service life of the ball-screw is too short.

- The maintenance work is too labor-intensive.
- The drive mechanism requires too much space.

etc.

Cost reduction is achieved, compared with electric drive systems!

One electro-hydraulic hybrid system can drive a plurality of actuators at a time. Therefore, the number of electric motors can be decreased. (Depending on the nature of the entire system, the number of necessary electric motors may not be decreased.) When used in conjunction with a variable displacement pump, ECO SERVO helps decrease the necessary capacities of the electric

motors as well as the necessary driving torque.

Simple configuration contributes to improved maintainability!

Unlike electrically driven systems, you are spared the replacement works of ball-screw and/or maintenance for grease.

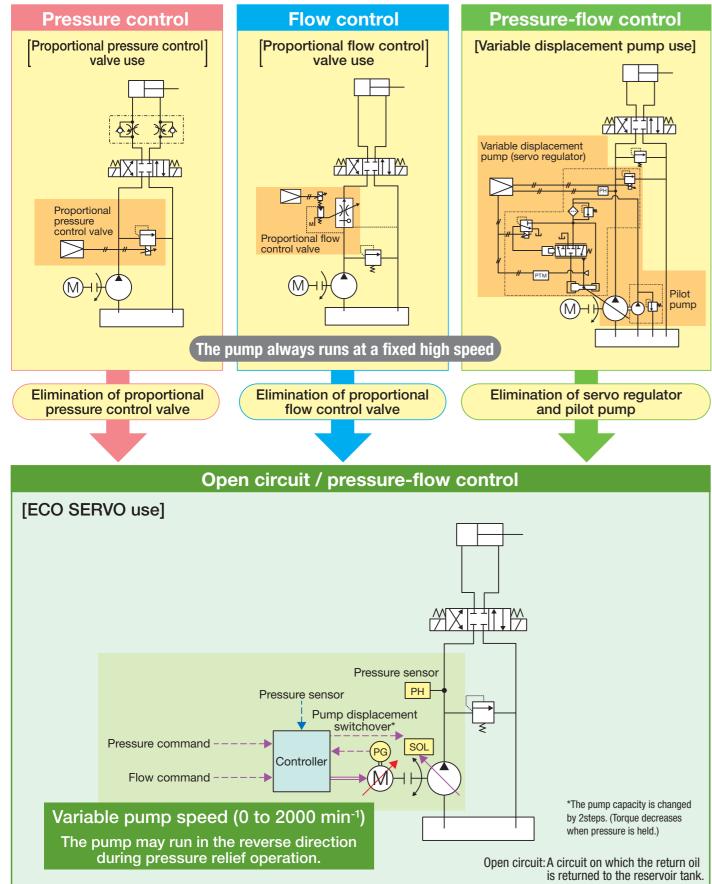
Since the hydraulic circuit is simple, the number of components that require time-consuming adjustment works can be decreased. Unlike servo-valve system, strict maintenance works of hydraulic fluid are not necessary.

Reduced space needed for the entire system!

The hydraulic power transmission system enables flexible layout design. This results in a compact design for the entire system. The decreased loss of energy leads to less heat generation, and this allows the capacities for hydraulic fluid, fluid tank and cooler to be much smaller.

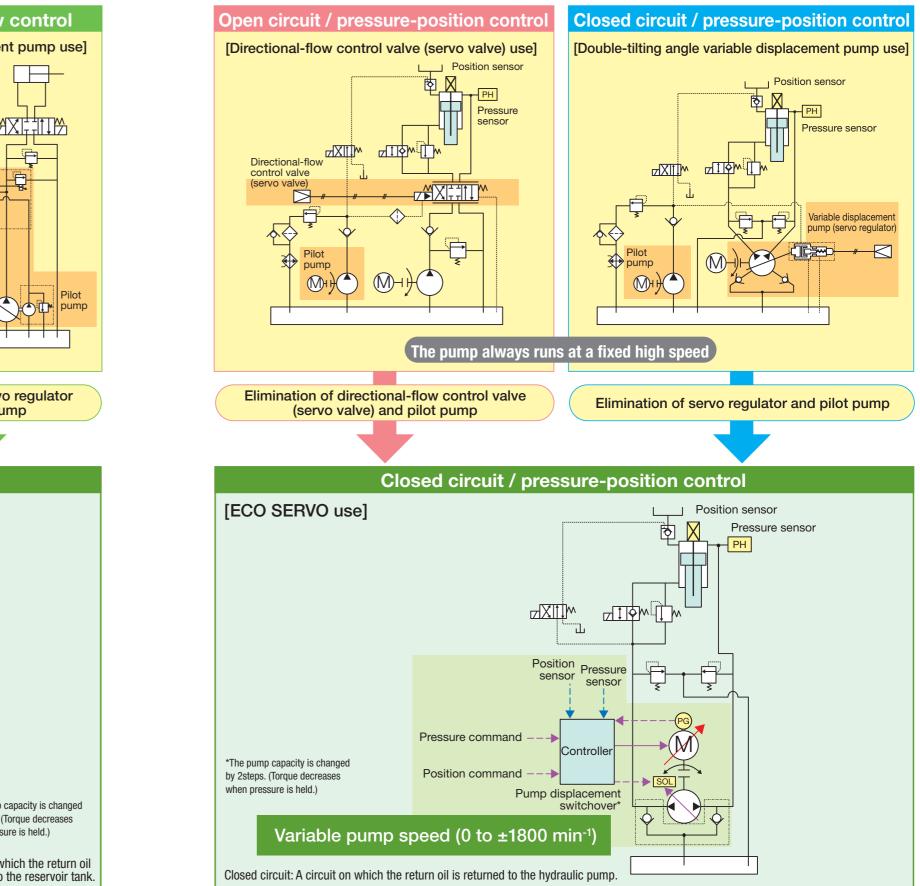
Examples of ordinary open circuit

Incorporation of ECO SERVO contributes to elimination of components otherwise needed on conventional hydraulic circuits—for example, proportional pressure control valves and flow control valves as well as servo regulators and pilot pumps for variable displacement pumps.



Examples of typical closed circuit for press machine

Elimination of a servo valve or servo regulator and pilot pump and other elements for the hydraulic pump leads to a unique hydraulic circuit that realizes higher output, decreased energy consumption and compact size.



The unique lineup of products can cope with requirements for a diversity of systems.

Making the most of the high performance hydraulic pumps with the capacity of high pressure, low fluctuation and high efficiency, ECO SERVO covers a wide range of displacement.

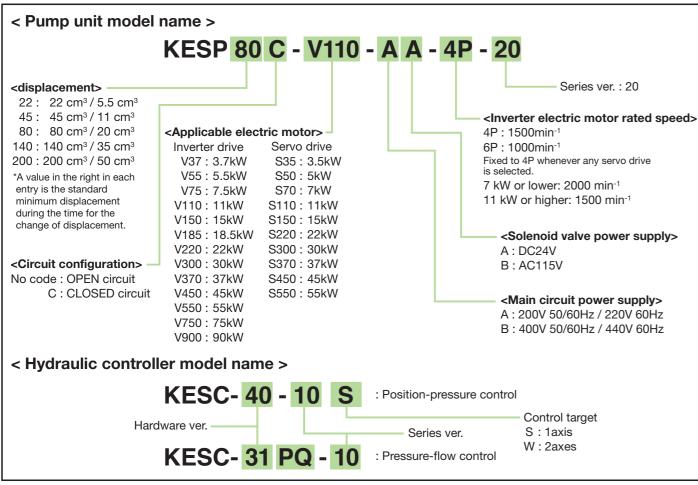
Pump di	splacement	cm ³	2	2	4	5	8	0	14	40	2	00	500
	Motor capacity	kW	7.5	11	22	30	30	37	45	55	75	90	
Inverter drive	Rated torque *2	N∙m	47.7	70	140	191	191	235	286	350	477	572	
	Max. torque *3	N∙m	71.6	105	211	287	287	353	429	525	715	858	
Servo drive	Motor capacity	kW	5	7	7	11	11	15	37	45	45	55	The pump displacement of
	Rated torque *2	N∙m	23.9	33.4	33.4	70	70	95.5	236	286	286	350	500 cm ³ is individually
	Max. torque *3	N∙m	71.6	100	100	210	210	286	707	859	859	1,050	available. When considering this
Pump	Max. operating	MPa	32 1								capacity, contact Kawasaki Precision Machinery.		
pressure	Peak	MPa	35								Wachiniery.		
Max. speed *4 min ⁻¹		2,000 (for Open Circuit), 1,800 (for Closed Circuit) 1,800											
Hydraulic fluid type			Antiwear hydraulic fluid *5										
Supply voltage/frequency			200 to 230V, 380 to 480V 50/60Hz										

*1: When considering other combination of pump displacement and motor capacity, contact Kawasaki Precision Machinery.

*2: Rated speed of the electric motor is 1500 min⁻¹. (2000 min⁻¹ only when the servo drive is rated at 5 kW or 7 kW)

*3: The max. torque values are short-time rating values. Be sure to select the appropriate servo or inverter drive such that the effective torque value for each cycle is below the corresponding rated torque.

*4: The max. speed might be subject to the limit depending on various conditions such as the use conditions and operating cycle. *5: When wanting to use a hydraulic fluid not specified above, contact Kawasaki Precision Machinery for technical assistance.



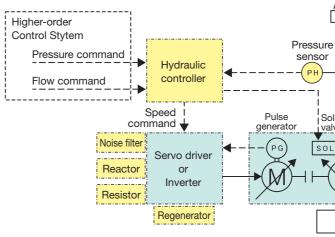
*6: For detailed information about the constituent components of the above-mentioned pump unit types, refer to the System Configuration section in the next page

Possible System Configurations

Capable of applications to various systems

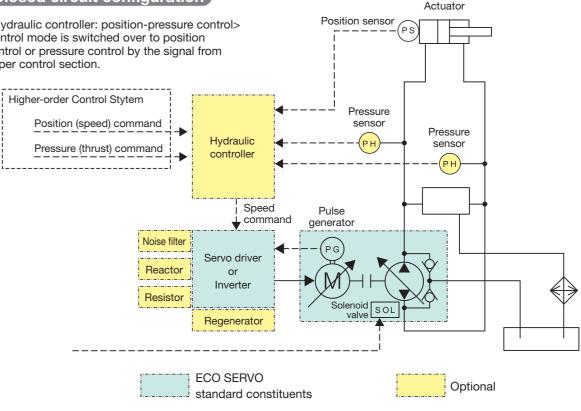
Open circuit configuration

<Hydraulic controller: pressure-flow control> When the pressure does not increase to the commanded level when the entire system is under a light load, the entire system is controlled based on the flow command.



Closed circuit configuration

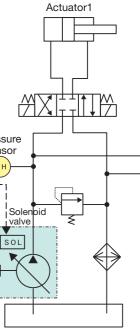
<Hydraulic controller: position-pressure control> Control mode is switched over to position control or pressure control by the signal from upper control section.

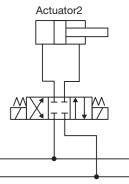


<ECO SERVO standard constituents> •Pump (with displacement switchover solenoid valve), •Electric motor, •Inverter or servo driver, •Coupling, •Bracket with resilient support

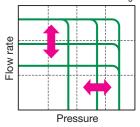
<Optional>

•Hydraulic controller, •Noise filter, •DC reactor, •Braking resistor, •Power regenerator, •Cables and connectors for pulse generator, •Cables and connectors for servo driver, •Pressure sensor

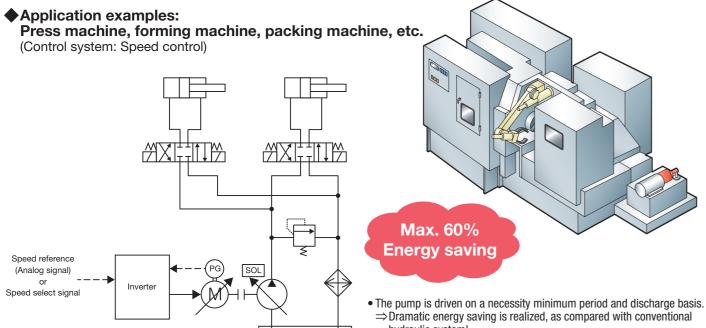




Pressure-flow rated characteristics (Pressure-flow characteristics are controlled in accordance with an electric signal.)



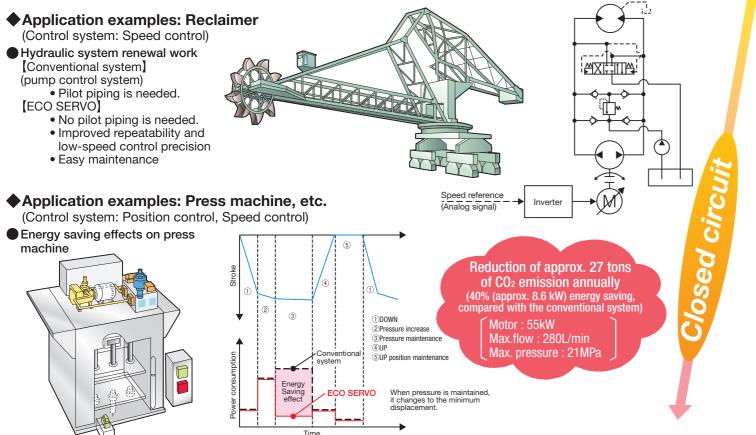
Typical Examples of Open Circuit with Inverter Drive

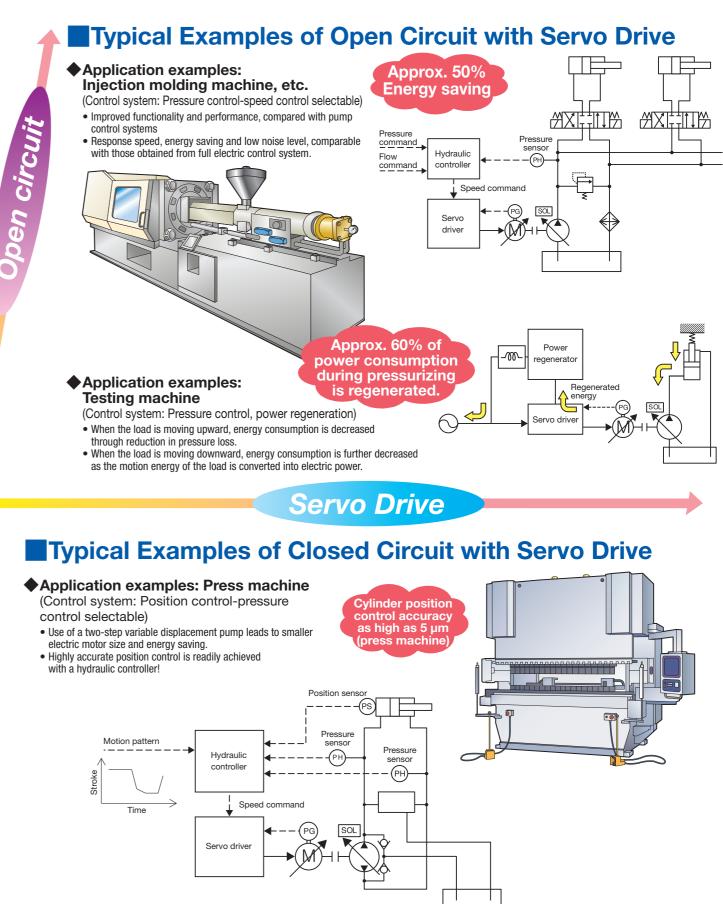


- \Rightarrow Dramatic energy saving is realized, as compared with conventional hvdraulic system (10 to 30% energy saving even when a variable displacement pump
- is used)
- \Rightarrow Lower average noise level
- Inverter control contributes to improved operability and controllability at lower speed range.

Inverter Drive

Typical Examples of Closed Circuit with Inverter Drive

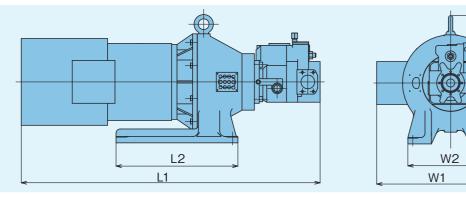




- Application examples: Propeller pitch controller, etc. (Control system: Position control)
- . Unlike servo-valve system, strict maintenance works of hydraulic fluid are not necessary.
- Since direction valves are unnecessary, the system is compact.

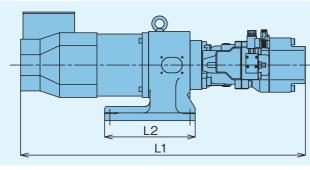
External Dimensions

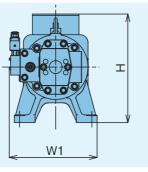
Pump unit (for open circuit / inverter drive)



Туре	Motor	L1 (mm)	L2 (mm)	W1 (mm)	W2 (mm)	H (mm)	Mass (kg)
KESP45-V*	30kW	1,320	570	571	400	600	395
KESP80-V*	37kW	1,360	570	571	400	600	410
KESP140-V*	55kW	1,660	660	653	550	710	625

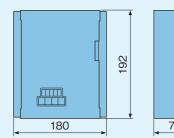
Pump unit (for closed circuit / servo drive)

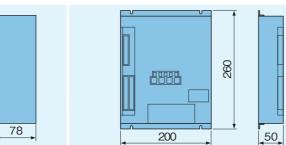




Туре	Motor	L1 (mm)	L2 (mm)	W1 (mm)	H (mm)	Mass (kg)
KESP45C-S*	11kW	920	350	320	410	170
KESP80C-S*	15kW	1,080	350	320	410	200
KESP140C-S*	45kW	1,380	450	440	490	415
KESP200C-S*	55kW	1,560	500	460	580	550

Hydraulic controller KESC-**-** (optional)





Item	KESC-40-10	KESC-31PQ-10
Power supply	DC24V	DC24V
Command-sensor input	Position signal (analog/digital) Pressure signal (analog) Flow signal (analog)	Pressure signal (analog) Flow signal (analog)

*1: For information about the external dimensions of the inverter and servo driver, contact Kawasaki Precision Machinery. *2: For information about the detailed specification for the hydraulic controller, contact Kawasaki Precision Machinery.

Optional Equipment

A full lineup of optional equipment allows the users to build a diversity of systems.

Name of optional equipment	Typical applications	Selection practice and considerations
Hydraulic controller	This controller calculates a pump speed based on the position, speed and pressure commands, and outputs a speed command to a motor driver.	Employ the hydraulic controller when wanting to isolate the hydraulic control system from the upper control section and construct a self-contained control system within the hydraulic system. Two types of hydraulic controller are available—position- pressure controller and pressure-flow controller. Select either type that is suitable for the intended hydraulic system.
Noise filter	The noise filter can suppress the noise occurring from the motor driver.	Troubles deriving from electrical noise can be positively prevented through basic noise countermeasures including noise-immune wiring arrangement and grounding work when designing the control panel. If a noise-derived problem occurs, it is necessary to select noise-immune equipment that helps solve the problem.
DC reactor	The DC reactor helps improve the input power factor for the motor driver and suppress the input higher harmonic current.	Use a DC reactor when the power supply capacity is larger relative to the motor driver capacity or a measure against harmonic current is needed.
Braking resistor	When braking torque is necessary on the motor driver circuit, the braking resistor converts the energy from the load side into heat to provide a braking torque.	A braking resistor must be incorporated when load torque and the losses of the motor driver and motor are not enough to provide the necessary braking torque. If an over-voltage alarm occurs on the motor driver when the motor is decelerating, then a braking resistor must be installed or it is necessary to decrease braking torque.
Power regenerator	The regenerator converts the braking energy from the load side into electricity and feeds this electricity to the power supply system, so that energy saving effect is further enhanced.	An electric regenerative system will be useful when the entire hydraulic system is frequently shut down and the amount of recovered electric power is large. When an electric regenerative system is incorporated, a braking resistor is no more necessary.

*1: For information about selection of specific optional equipment models, contact Kawasaki Precision Machinery.

Operating precautions

1. Considerations about selection of electric motor capacity

To determine the capacity of the electric motor that is used in conjunction with the hydraulic pump, use the following formula:

Required torque (N·m)	$T = \frac{q \cdot \Delta p}{2\pi \cdot \eta_{m}}$
Output power (kW)	$N = \frac{2\pi \cdot T \cdot n}{60,000} = \frac{T}{9,9}$
	_ Q·∆p
	$=$ $60 \cdot \eta_t$

For the instantaneous max, torgue and continuous rated torgue with the intended electric motor, refer to the specification table in page 5.

For information about the displacement of pump that is capable of displacement switchover, refer to the field for the intended pump model in the table within page 5. The capacity of electric motor can be decreased through displacement switchover.

2. Measures against noise occurrence

When housing the motor driver in the control panel, and when installing the control panel, provide in advance basic noise control measures which include: [1] isolation of the control circuit from the main electrical power circuit, [2] reliable grounding work, [3] use of shielded cables for the control circuit, and [4] use of metal conduit for the main electrical power circuit.

3. Precautions for using the pump

There are precautions for using the hydraulic pumps, and which include the external drain piping work, kind of hydraulic fluid, and cautions for operating the pump. For more details, refer to the catalog or instruction manual dedicated to the axial piston pump (K3VR, K3VL, K7VG series) for general industrial machinery.

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q : Displacement [cm³] Δp : Effective pressure [MPa] $\eta_{\rm m}$: Pump machine efficiency n : Speed [min-1] Q : Output flow [L/min] η_{t} : Pump total efficiency